



Future
Mobility
Network



The Autonomous Future

A realistic perspective

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The Autonomous Future



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Introduction

Founder of The Future Mobility Network

Projectleader of

- The WEpods project
- The AVLM project in the MRDH region
- The Researchlab Automated Driving TU Delft

Projectdesigner for

- The Interreg IAT project
- ADaaS



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But also...

- Drones in the City



- Buurautonom
- Pizza delivery robot





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WEpods

The world's first automated vehicle (AV):

- On public roads
- No steering wheel
- No brake pedal
- No driver → ???

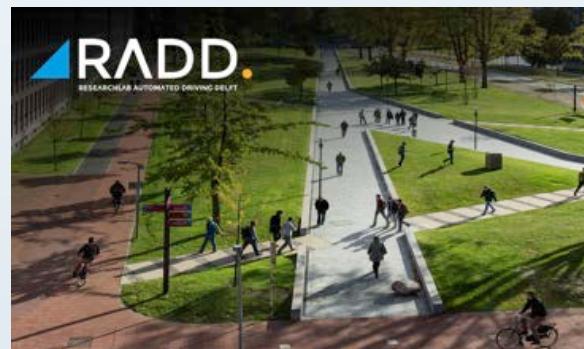
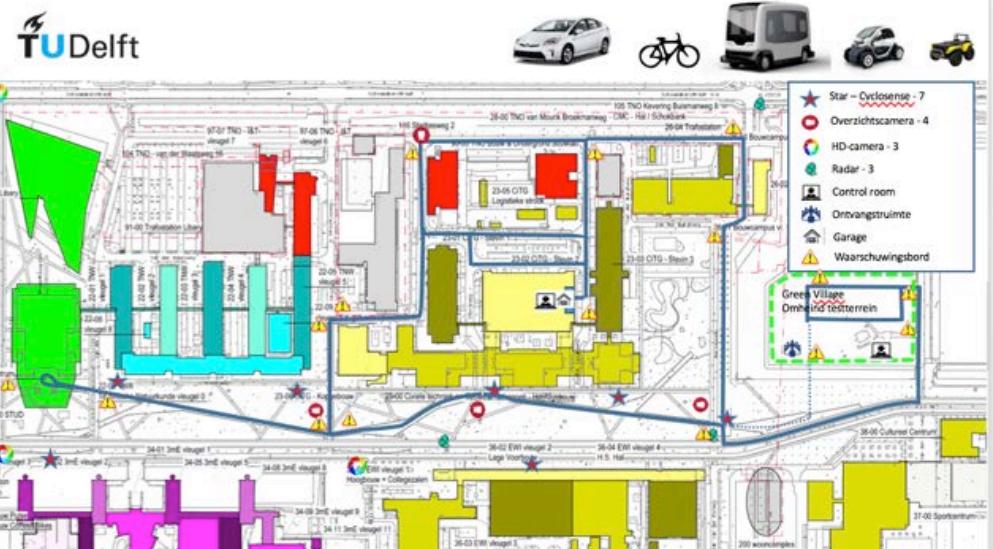




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Researchlab Automated Driving Delft

- Researchlab
- Testing with different platforms
- Closed and public terrain





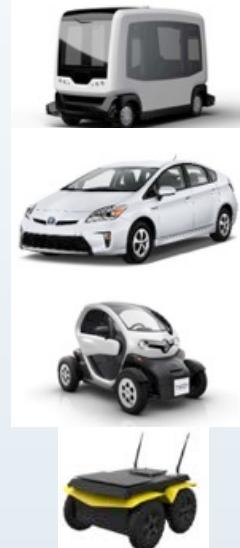
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LOCATION



FLEET



PARTNERS





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Researchlines



Vehicle functioning



Interaction &
acceptation



User experience



Public Transit



Goods transport



Trafficsystem

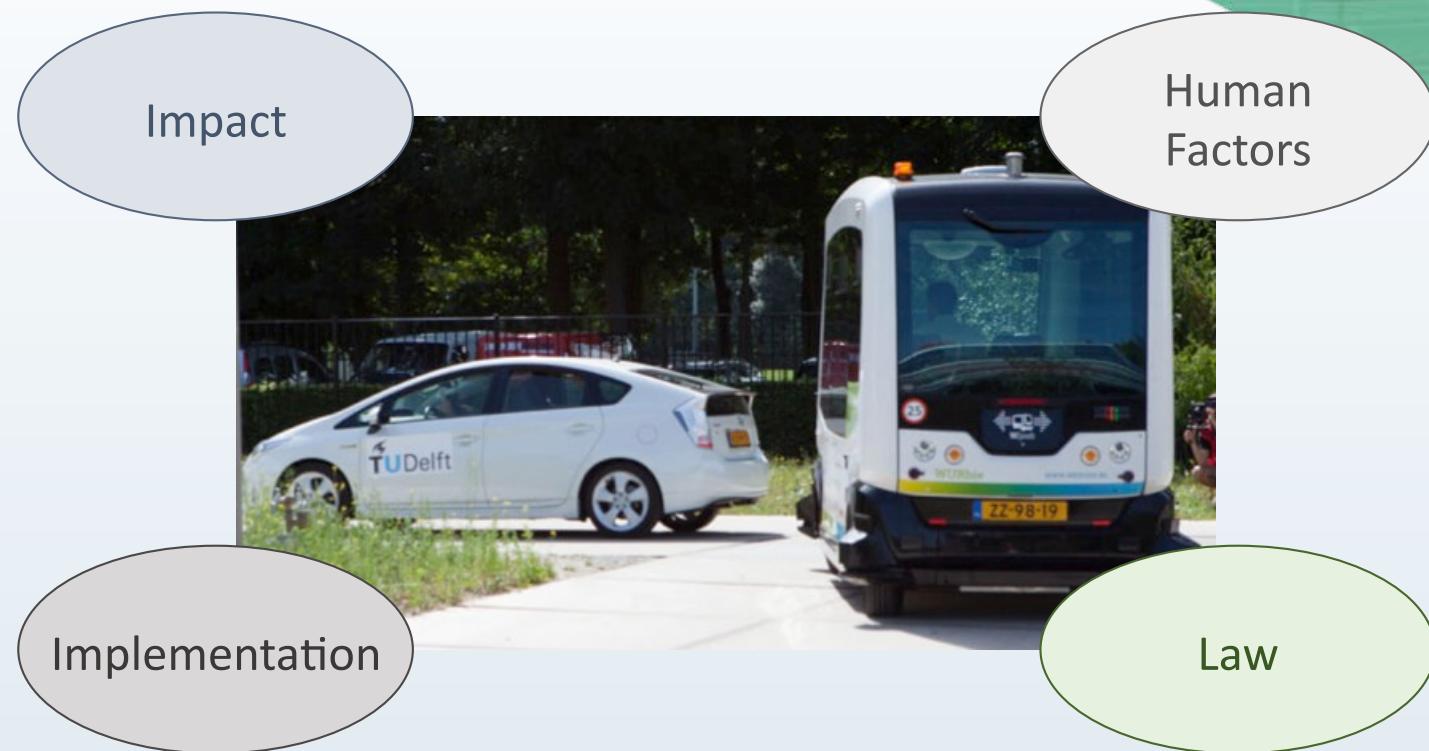
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Knowledge agenda Automated Driving





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Human factors

Human
Factors

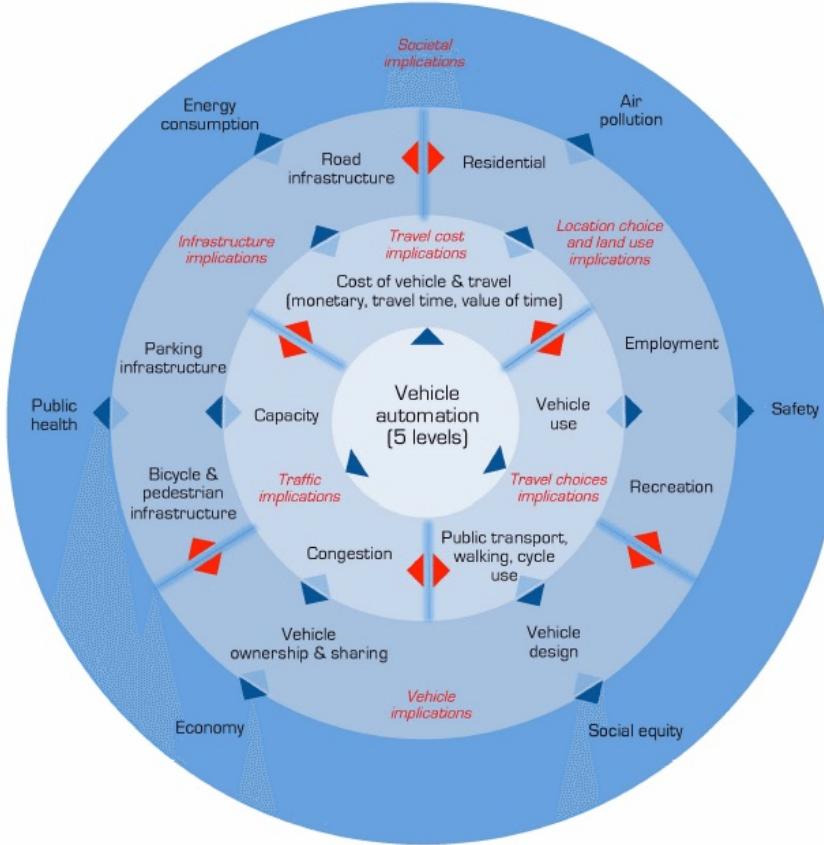
- Trust in technology?
- Interaction between road users and AV's
- To what extent do humans still have to think along, steer?





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AV's in gebruik



Impact